

zub Practical Seminar

This practical seminar will introduce you to the exciting new innovations from the new generation of MACS motion controllers. Be on hand for the first presentation of our latest development from the **MACS6 family of products**. We'll inform you about the most important benchmark data and combination options. We're constantly transforming our know-how into do-how, and we'll show you effective application tricks from practical experience.

zub has added kinematic commands to both the APOSS Path Editor and the Motion Control Library. The MACS Motion Controller enables you to define and apply **robotic kinematics**. Learn how to program the X/Y tables, Scara, DualScara and Delta-Robots effectively. See for yourself how programming complex path curves can become so much easier.

There's even a **Linux Library** to assist you in linking the MACS Motion Controller to Linux. In the seminar we'll show you how this works and how you can efficiently employ the library in your everyday work.



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